

Ricardo Omar **Chavez-Garcia**

Born in Oaxaca, Mexico
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Researcher at Cognitive and Mobile Robotics Research Group

Dalle Molle Institute for Artificial Intelligence Research (IDSIA)
University of Applied Sciences and Arts
of Southern Switzerland (SUPSI)
Galleria 2, Via Cantonale 2c
CH-6928 Manno
Switzerland

Research Interests

I am interested in proposing and developing intelligent systems for robotic platforms that interact with the real world. I work on stochastic approaches for robotic perception and interaction. My research perspectives concern the environment understanding and learning of sensorimotor representations for decision-making tasks.

Research and Development Experience

*Cognitive
Robotics*
2017-current

Research on cognitive models for robotic knowledge discovery – *Dalle Molle Institute for Artificial Intelligence Research (IDSIA)* – Lugano, Switzerland

Integration of cognitive approaches and uncertain information in knowledge discovery for robotic applications. Member of The Swiss National Centre of Competence in Research for Robotics (NCCR-Robotics) research consortium for developing new types of flying, walking, and swimming robots and human interactions for disaster areas or in normal life for exploration and transportation.

www.idsia.ch | www.nccr-robotics.ch

*Developmental
Robotics*
2015-2017

Research and Development of a Cognitive Perception System for Situation awareness and Semantic Scene Interpretation – *Institut des Systèmes Intelligents et de Robotique (ISIR)* – Paris, France

Proposal and development of an active cognitive perception system for modelling the environment by integrating action and perception processes. www.isir.upmc.fr | www.roboergosum.isir.upmc.fr

*Autonomous
Vehicles*
2011-2014

Responsible for the Perception Process in the *interactIVe (accident avoidance by active intervention for Intelligent Vehicles) IP European Project* – Grenoble, France

Proposal and development of a multi-sensor fusion solution for vehicle frontal object perception applications. It involved: outdoor environment mapping and localization; and detection, tracking and classification of multiple objects of interest in different driving scenarios. www.interactive-ip.eu

*Robotic
Platforms*
2012-2014

Responsible for the Robotic Platforms – *Machine Learning Team (AMA) Grenoble Informatics Laboratory (LIG)* – Grenoble, France

Development of robotic drivers and sensor (mono-camera and 2D lidar scanner) data processing modules for Wifibot and Nao robotic platforms. www.liglab.fr

Education

*Ph.D. in
Mathematics and
Computer
Science*
2010-2014

University of Grenoble 1 (Université Joseph Fourier), Grenoble, France

Thesis: *Multiple Sensor Fusion for Detection, Classification and Tracking of Moving Objects in Driving Environments*

Description: Two multi-sensor fusion approaches were proposed to include classification information from different sources of evidence in a whole perception solution. Uncertainty and imprecision from sensor measurements, object detections and object classification process were considered as key factors to improve the final perception output.

Thesis Advisor: Olivier AYCARD, Ph.D.

*Master in
Computer
Science*
2008–2010

National Institute of Astrophysics, Optics and Electronics, Puebla, Mexico

Thesis: *Re-ranking of retrieved images using a combination of visual and textual features*

Description: A multiple modal approach was proposed to represent images using textual and visual features. This approach uses a multi-modal representation to re-rank a list of retrieved images by

applying Markov Random Fields.

Thesis advisors: Manuel MONTES-Y-GOMEZ, Ph.D. and Luis Enrique SUCAR, Ph.D.

Technological University of Mixteca, Oaxaca, Mexico

Thesis: *Coordinated Construction of Ontologies for Documents Ranking*

Description: Development of a software infrastructure for building knowledge repositories using ontological representations.

Thesis advisor: M. Auxilio MEDINA, Ph.D.

Publications

Learning Ground Traversability from Simulations. R. Omar Chavez-Garcia, Jerome Guzzi, Alessandro Giusti, Luca M. Gambardella. IEEE Robotics and Automation Letters, vol. 3, issue 3, pp. 1695-1702. 2018.

Affordance Equivalences in Robotics: A Formalism. Andries, Mihai, Chavez-Garcia, Ricardo Omar, Chatila, Raja, Giusti, Alessandro, and Gambardella, Luca Maria. Frontiers in Neurorobotics, vol. 12. 2018.

Image Classification for Ground Traversability Estimation in Robotics. R. Omar Chavez-Garcia, Jerome Guzzi, Alessandro Giusti, Luca M. Gambardella. Advanced Concepts for Intelligent Vision Systems, pp. 325-336. 2017

Discovering and Manipulating Affordances. R. Omar Chavez-Garcia, Mihai Andries, Raja Chatila and Pierre Luce-Vayrac. The 2016 International Symposium on Experimental Robotics (ISER 2016). -to appear-

Discovering Affordances Through Perception and Manipulation. R. Omar Chavez-Garcia, Raja Chatila and Pierre Luce-Vayrac. 2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2016), pp. 3959-3964. October 2016

From Perception and Manipulation to Affordance Formalization. R. Omar Chavez-Garcia, Mihai Andries, Pierre Luce-Vayrac and Raja Chatila. Workshop on Machine Learning Methods for High-Level Cognitive Capabilities in Robotics 2016, Daejeon, South Korea.

Multiple Sensor Fusion and Classification for Moving Object Detection and Tracking. Ricardo Omar Chavez-Garcia, Olivier Aycard. IEEE Transactions on Intelligent Transportation Systems, vol. 17, issue 2, pp. 252-534. September 2015.

Multiple Sensor Fusion for Detection, Classification and Tracking of Moving Objects in Driving Environments. R. Omar Chavez-Garcia. Ph.D Thesis, 2014. University of Grenoble1

Fusion at Detection Level for Frontal Object Perception. R. Omar Chavez-Garcia, Trung-Dung Vu, Olivier Aycard and Fabio Tango. IEEE Intelligent Vehicles Symposium (IV), 2014

Research Report on Sensor Data Fusion. Anastasia Bolovinou, Angelos Amditis, Nikos Floudas, Christina Kotsiourou, Trung-Dung Vu, R. Omar Chavez-Garcia, Olivier Aycard, Fabio Tango, Mario DallaFontana, Chris Benson, Nils Appenrodt, Markus Schutz, Sebastian Pangerl, Florian Janda, Erich Fuchse, Lali Ghosh, Mirko Meuter, Daniel Schuck and Christian Nunn. 7th Framework Programme ICT-2009.6.1: ICT for Safety and Energy Efficiency in Mobility Grant Agreement No. 246587 Large-scale Integrated Project. InteractIve Project Consortium, 2013

Fusion framework for moving-object classification. R. Omar Chavez-Garcia, Trung-Dung Vu, Olivier Aycard and Fabio Tango. 16th International Conference on Information Fusion (FUSION), pp. 1159-1166, 2013

Multimodal Markov Random Field for Image Reranking Based on Relevance Feedback. R. Omar Chavez-Garcia, Hugo Jair Escalante and Luis Enrique Sucar. ISRN Machine Vision, vol. 2013, February 2013.

Frontal Object Perception Using Radar and Mono-Vision. R. Omar Chavez-Garcia, Julien Burlet, Trungdung Vu and Olivier Aycard. IEEE Intelligent Vehicles Symposium (IV), pp. 159-164, 2012

Using a Markov Random Field for Image Re-ranking Based on Visual and Textual Features. R. Omar Chavez-Garcia, Manuel Montes and L. Enrique Sucar. Computación y Sistemas Vol. 14, No. 4, 2011.

A Probabilistic Method for Ranking Refinement in Geographic Information Retrieval. Esau Villatoro-Tello, R. Omar Chavez-García, Manuel Montes-y-Gómez, Luis Villaseñor-Pineda, L. Enrique Sucar. Procesamiento de Lenguaje Natural, No. 44, pp. 123-130, April 2010.

Image Re-Ranking Based on Relevance Feedback Combining Internal and External Similarities. R. Omar Chavez-Garcia, Manuel Montes-y-Gómez, Luis Enrique Sucar. In proceeding of: Proceedings of the Twenty-Third International Florida Artificial Intelligence Research Society Conference. May 19-21, 2010, Daytona Beach, Florida.

RDF-Based Model For Encoding Document Hierarchies. Ma. Auxilio Medina J., Alfredo Sanchez and R. Omar Chavez-Garcia. Proceedings of the 17th International Conference on Electronics, Communications and Computers (CONIELECOMP). Puebla, Mexico, 2007.

Construction, Implementation and Maintenance of Ontologies of Records. Ma. Auxilio Medina, Alberto Chavez Aragon, and R. Omar Chavez-Garcia. In Proceedings of the Fourth Latin American Web Congress (LAWEB). Puebla, Mexico, May 2006.

Copyrighted Software Solutions

- 2014 Multi-sensor Frontal Object Perception
S105 - FOP - *Frontal Objects Perception (P032)* - IDDN.FR.001.180016.000.S.C.2014.000.20700
- 2014 Multi-sensor Moving Object Classification
S106 - MOC - *Moving Objects Classification (P033)* - IDDN.FR.001.180017.000.S.C.2014.000.20700

Academic Activities

- Teaching assistant Master*
Fall, 2017 Master in Artificial Intelligence - Università della Svizzera italiana
Robotics
- Co-supervisor*
Fall 2016 Master 2 integrative project "Surveillance system for industrial safety in human-robo environments" – University Pierre and Marie Curie.
Proposal and supervision of a machine learning approach for detecting and tracking moving agents (humans and industrial robots) in robotic environments.
- Co-supervisor*
Fall 2016 Master 1 internship: Robot visual self-recognition – University Pierre and Marie Curie.
Proposal and supervision of a probabilistic approach for robot self-recognition using visual flow.
- Teaching assistant Master*
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Fall, 2016 Master Science Technologies, Santé (Engineering Sciences) - University Pierre and Marie Curie
Pattern Recognition
- Teaching assistant Master*
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Fall, 2016 Master Science Technologies, Santé (Engineering Sciences) - University Pierre and Marie Curie
Programming on Linux Systems
- Co-supervisor*
Fall, 2015 Master 2 Integrative project "Stereo Vision Module for Parallel Architectures" for Master1 degree – University Pierre and Marie Curie.
Proposal and supervision of a Software-Hardware module for acquisition and processing of stereo data.
- Co-supervisor*
Spring, 2015 Master2 internship: Sensori-motor representations for interactive robots – University Pierre and Marie Curie.
Association of perceptual elements from visual sensors and proprioceptive data to create sensori-motor representations.
- Teaching assistant*
Fall, 2012 Informatique instrumentale et multimédia · Université Joseph Fourier
Theory of Algorithms and Introduction to Programming for undergraduate students.

Affiliations and Awards

- February 2018* NVIDIA GPU Grant – NVIDIA Corporation
- Donation of an embedded platform for autonomous and AI applications.
- February 2017* Qualification for university lecturer – French Ministry for National Education, Higher Education and Research

- Computer engineering, automatic control and signal processing
- Informatics

<i>April, 2016</i>	Member of the IEEE Technical Committee on Cognitive Robotics – IEEE Robotics and Automation Society
<i>January, 2014</i>	Member of The International Society of Information Fusion
<i>November, 2010</i>	Best Master in Science thesis on Artificial Intelligence Award Granted by Mexican Society for Artificial Intelligence, for the thesis: 'Re-ranking of retrieved images using a combination of visual and textual features'
<i>November, 2009</i>	Best Student in Master in Computational Sciences Program Award Granted by the National Institute of Astrophysics Optics and Electronics, for an outstanding academic performance
<i>November, 2008</i>	Master in Science Scholarship Scholarship by the Mexican National Council of Science and Technology (CONACyT)

Computer Skills

<i>Programming</i>	C++, Python, Javascript, PHP, Shell scripting, R, Java
<i>Laboratory Platforms</i>	ROS, Matlab

Communication Skills

<i>Languages</i>	<i>English</i> · Professional proficiency
	<i>French</i> · Professional proficiency
	<i>Spanish</i> · Mother tongue

Reviewing activities

Invited reviewer for:

- *IEEE Transactions on Intelligent Transportation Systems 2015, 2016, 2017, 2018*
- *IEEE Robotics and Automation Letters 2018*
- *IEEE International Conference on Robotics and Automation 2016, 2017*
- *IEEE/RSJ International Conference on Intelligent Robots and Systems 2015, 2016, 2017*
- *Intelligent Vehicles Symposium 2014, 2015, 2016, 2017, 2018*
- *Elsevier Computer Networks Journal 2016*
- *IEEE 18th International Conference on Intelligent Transportation Systems 2015*
- *Seventh International Conference on Social Robotics 2015*